

BENHA UNIVERSITY FACULTY OF ENGINEERING AT SHOUBRA

ECE-322 Electronic Circuits (B)

Lecture #7 Voltage Regulators

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VOLTAGE REGULATION



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Intro.

- **Two** basic **categories** of voltage regulation are:
 - Line regulation
 - Load regulation
- The purpose of line regulation is to maintain a nearly constant output voltage when the input voltage varies.
- The purpose of load regulation is to maintain a nearly constant output voltage when the load varies.



Line Regulation

- When the ac input (line) voltage of a power supply changes, an electronic circuit called a **regulator** maintains a nearly constant output voltage.
- Line regulation can be defined as the percentage change in the output voltage for a given change in the input voltage



Load Regulation

- Load regulation can be defined as the percentage change in output voltage for a given change in load current.
- One way to express load regulation is as a percentage change in output voltage from no-load (NL) to full-load (FL).



BASIC LINEAR SERIES REGULATORS

Regulators Classification

- The fundamental classes of voltage regulators are:
 - linear regulators
 - switching regulators
- Both of these are available in integrated circuit form.
- Two basic types of linear regulator are
 - series regulator
 - shunt regulator

Series Voltage Regulator





Basic op-amp series regulator



Regulating Action

- Illustration of series regulator action that keeps V_{OUT} constant when V_{IN} or R_{L} changes.



(a) When $V_{\rm IN}$ or R_L decreases, $V_{\rm OUT}$ attempts to decrease. The feedback voltage, $V_{\rm FB}$, also attempts to decrease, and as a result, the op-amp's output voltage $V_{\rm B}$ attempts to increase, thus compensating for the attempted decrease in $V_{\rm OUT}$ by increasing the Q_1 emitter voltage. Changes in $V_{\rm OUT}$ are exaggerated for illustration.

When $V_{\rm IN}$ (or R_L) stabilizes at its new lower value, the voltages return to their original values, thus keeping $V_{\rm OUT}$ constant as a result of the negative feedback.



(b) When $V_{\rm IN}$ or R_L increases, $V_{\rm OUT}$ attempts to increase. The feedback voltage, $V_{\rm FB}$, also attempts to increase, and as a result, $V_{\rm B}$, applied to the base of the control transistor, attempts to decrease, thus compensating for the attempted increase in $V_{\rm OUT}$ by decreasing the Q_1 emitter voltage.

When V_{IN} (or R_L) stabilizes at its new higher value, the voltages return to their original values, thus keeping V_{OUT} constant as a result of the negative feedback.

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Short-Circuit or Overload Protection

- If an excessive amount of load current is drawn, the series-pass transistor can be quickly damaged or destroyed.
- Most regulators use some type of excess **current protection** in the form of a current-limiting mechanism.
- one method of current limiting to prevent overloads called constant-current limiting.





REGULATORS ¹²

BASIC LINEAR SHUNT REGULATORS



Shunt Regulator

• In the shunt regulator, the control element is a transistor in parallel (shunt) with the load.



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Regulating Action

• Sequence of responses when V_{OUT} tries to decrease as a result of a decrease in R_L or V_{IN} (opposite responses for an attempted increase)



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INTRO. TO SWITCHING REGULATORS

Switching Regulators

- The two types of linear regulators, series and shunt, have control elements (transistors) that are conducting all the time, with the amount of conduction varied as demanded by changes in the output voltage or current.
- The **switching regulator** is different because the **control element** operates as a **switch**.
- A much greater efficiency can be realized with a switching type of voltage regulator than with the linear types because the transistor switches on and off and dissipates power only when it is on.
- Efficiencies can be greater than **90%**.
- Three basic configurations of switching regulators are step-down, step-up, and inverting.
- In some cases, such as a laptop computer, all three types may be employed for various parts of the system.
- For example, the display typically will use an inverting type, the microprocessor would use a step-down type, and the disk drive may use a step-up type.

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- For more details, refer to:
 - Chapter 17, T. Floyd, **Electronic Devices**, 9th edition.
- The lecture is available online at:
 - http://bu.edu.eg/staff/ahmad.elbanna-courses/12135
- For inquires, send to:
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